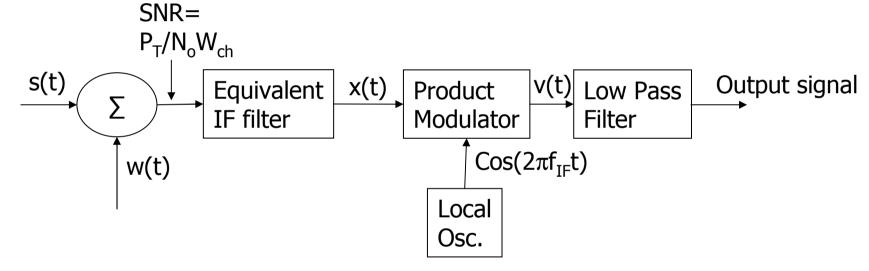


## **Communication Systems II**

Noise in CW modulation SSB, QAM, Envelope Detection



 The IF filter output is multiplied by a local carrier with frequency f<sub>IF</sub> and then low pass filtering the product



• Consider SSB-LSB  $s(t) = \frac{A_c}{2} m(t) \cos(2\pi f_c t) + \frac{A_c}{2} \hat{m}(t) \sin(2\pi f_c t)$  where m(t) is considered a sample function of a stationary process of zero mean and PSD S<sub>M</sub>(f) limited to maximum frequency W



- m(t) and m<sup>^</sup>(t) are orthogonal to each other.
  - If m(t) is zero mean → m(t) and m^(t) are uncorrelated
  - Their PSD are additive
  - m<sup>^</sup>(t) is obtained by passing m(t) on a LTIS with H(f)=-jsgn(f) → square magnitude is equal to one → m<sup>^</sup>(t) have the same PSD as m(t)

$$z = m(t) + \hat{m}(t)$$

$$R_z(t) = E[z(t)z(t+\tau)]$$

$$= E[m(t)m(t+\tau)] + E[\hat{m}(t)\hat{m}(t+\tau)] + zeros$$

$$R_z(\tau) = R_m(\tau) + R_{\hat{m}}(\tau)$$

$$S_z(f) = S_m(f) + S_{\hat{m}}(f)$$



- Inphase component \$\frac{A\_c}{2}m(t)\cos(2\pi f\_c t)\$
   Quadrature component \$\frac{A\_c}{2}\hat{m}(t)\sin(2\pi f\_c t)\$
   Average power in the inphase component = \$\frac{A\_c^2}{8}P\_m\$ average power in quadrature component=
   Average power in modulated signal s(t) = \$\frac{A\_c^2}{A}P\_m\$
- Half that of DSB-SC
- Channel noise power in message bandwidth is N<sub>o</sub>W

$$SNR_c = \frac{A_c^2 P_m}{4N_o W}$$

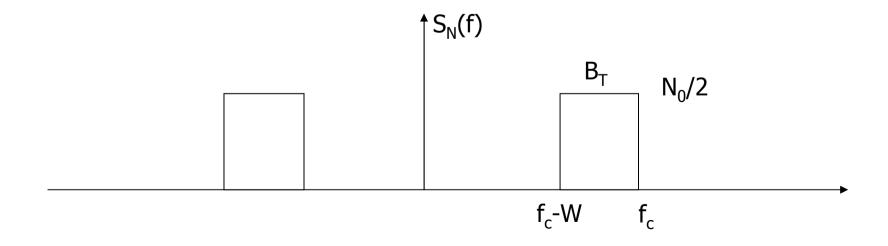


The NBN can be represented as

$$n(t) = n_c(t)\cos(2\pi(f_c - \frac{w}{2})t) - n_s(t)\sin(2\pi(f_c - \frac{w}{2})t)$$

The output of the coherent detector

$$y(t) = [s(t) + n(t)]\cos(2\pi f_c t)$$





#### The output of the coherent detector

$$y(t) = \frac{A_c}{2} m(t) \cos^2(2\pi f_c t) + \frac{A_c}{2} \hat{m}(t) \sin(2\pi f_c t) \cos(2\pi f_c t) + \frac{A_c}{2} m(t) \sin(2\pi f_c t) \cos(2\pi f_c t)$$

$$n_c(t)\cos(2\pi(f_c-\frac{w}{2})t)\cos(2\pi f_c t) - n_s(t)\sin(2\pi(f_c-\frac{w}{2})t)\cos(2\pi f_c t)$$

$$= \frac{A_c}{4}m(t) + \frac{A_c}{4}m(t)\cos(2\pi 2f_c t) + \frac{A_c}{4}\hat{m}(t)\sin(2\pi 2f_c t)$$

+

$$\frac{n_c(t)}{2}\cos(2\pi\frac{w}{2}t) + \frac{n_s(t)}{2}\sin(\frac{w}{2}t) + \text{higher frequency terms}$$



The output of the after LPF

$$= \frac{A_c}{4}m(t) + \frac{n_c(t)}{2}\cos(2\pi\frac{w}{2}t) + \frac{n_s(t)}{2}\sin(\frac{2\pi w}{2}t)$$

 $\frac{A_c^2}{16}P_m$ Average power in the detected message is

Average power in the received noise is

$$SNR_o = \frac{A_c^2 P_m}{16N_o W / 4} = \frac{A_c^2 P_m}{4N_o W}$$

$$= \frac{N_o W}{8} + \frac{N_o W}{8} = \frac{N_o W}{4}$$

Figure of Merit=1

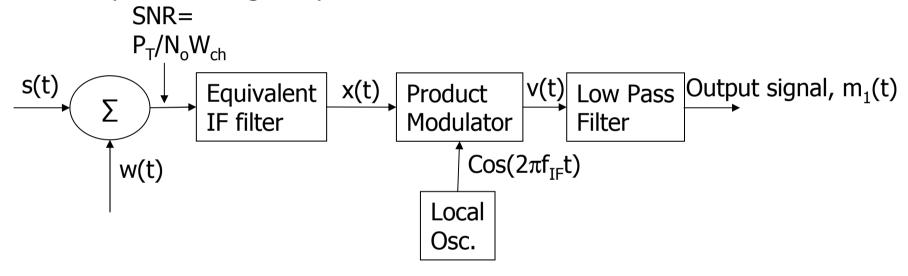


## Comparison between SSB, DSB-SC

- HW assignment
- Compare between the SNR of the DSB-SC, and the SSB



 The IF filter output is multiplied by a local carrier with frequency f<sub>IF</sub> and then low pass filtering the product



• Consider SSB-LSB  $s(t) = A_c m_1(t) \cos(2\pi f_c t) + A_c m_2(t) \sin(2\pi f_c t)$  where  $m_1(t)$  and  $m_2(t)$  are considered a sample functions of stationary processes of zero mean and PSD  $S_M(f)$  limited to maximum frequency W

$$s(t) = A_c m_1(t) \cos(2\pi f_c t) + A_c m_2(t) \sin(2\pi f_c t)$$

$$R_{s}(\tau) = \frac{A_{c}^{2}}{2} R_{m_{1}}(\tau) \cos(2\pi f_{c}\tau) + \frac{A_{c}^{2}}{2} R_{m2}(\tau) \cos(2\pi f_{c}\tau)$$

$$S_s(f) = \frac{A_c^2}{4} [S_{m_1}(f - f_c) + S_{m_1}(f + f_c) + S_{m_2}(f - f_c) + S_{m_2}(f + f_c)]$$

Received Signal

$$s(t) + w(t)$$

Received Signal after IF filter

$$X(t) = s(t) + n(t)$$

$$= A_c m_1(t) \cos(2\pi f_c t) + A_c m_2(t) \sin(2\pi f_c t) + n_c(t) \cos(2\pi f_c t) - n_s(t) \sin(2\pi f_c t)$$

$$= [A_c m_1(t) + n_c(t)] \cos(2\pi f_c t) + [A_c m_2(t) - n_s(t)] \sin(2\pi f_c t)$$

Received Signal after coherent detector

$$= [A_c m_1(t) + n_c(t)] \cos(2\pi f_c t) \cos(2\pi f_c t) + [A_c m_2(t) - n_s(t)] \sin(2\pi f_c t) \cos(2\pi f_c t)$$

Received Signal after LPF

$$[A_c m_1(t) + n_c(t)]/2$$

$$SNR_o = \frac{A_c^2 P_{m_1}}{2N_o W}$$

## Noise in AM receivers using Envelope Detection



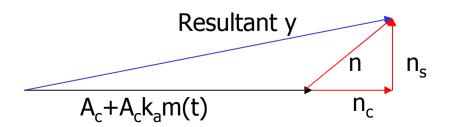
- The transmitted signal  $s(t) = A_c[1 + k_a m(t)] \cos(2\pi f_c t)$
- The average power in s(t) =  $A_c^2[1+k_a^2P_m]/2$
- The average noise power in the message bandwidth= N<sub>o</sub>W
- The  $SNR_{c,AM} = \frac{A_c^2[1 + k_a^2 P_m]}{2N_c W}$  The received signal at the envelope detector x(t) consists of the transmitted signal s(t) and NBN n(t)
- x(t) = s(t) + n(t) $= A_c[1 + k_a m(t)]\cos(2\pi f_c t) + n_c(t)\cos(2\pi f_c t) - n_s(t)\sin(2\pi f_c t)$  $= [A_c + A_c k_a m(t) + n_c(t)] \cos(2\pi f_c t) - n_s(t) \sin(2\pi f_c t)$

## Phasor diagram for AM wave plus NBN

From the phasor diagram, the received output y(t) is obtained as the envelope of x(t)

$$y(t) = \sqrt{[A_c + A_c k_a m(t) + n_c(t)]^2 + n_s^2(t)}$$

- Y(t) need to be approximated to a message term plus a noise and distortion term.
- If average carrier power is lager compared to noise, then the first term in y(t) will be larger than the second term  $y(t) \approx [A_c + A_c k_a m(t) + n_c(t)]$



## Phasor diagram for AM wave plus NBN

- DC component can be removed with DC block.
- The output signal to noise ratio

$$SNR_{o,AM} = \frac{A_c^2 k_a^2 P}{2WN_o}$$

- This expression is only valid IFF
  - The noise at the receiver input is small compared to the signal.
  - The K<sub>a</sub> is adjusted for a percentage modulation less than or equal to 100%
- The Figure of merit is always less than unity

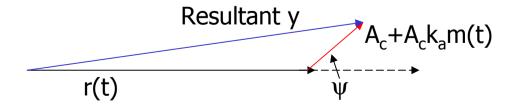
$$\frac{SNR_{o,AM}}{SNR_{c,AM}} = \frac{A_c^2 k_a^2 P}{2WN_o} \cdot \frac{2WN_o}{A_c^2 [1 + k_a^2 P]} = \frac{k_a^2 P}{[1 + k_a^2 P]}$$

#### The threshold effect

- When the signal to noise ratio is small, the noise component dominates and the performance of the envelope detector completely changes.
- NBN can be represented as shown

$$n(t) = r(t)\cos(2\pi f_c t + \psi(t))$$
Re *ceived* signal at envelope detector input
$$x(t) = s(t) + n(t)$$

• We can neglect the quadrature component of the signal  $y(t) \approx [r(t) + A_c \cos(\psi(t)) + A_c k_a m(t) \cos(\psi(t))]$ 





#### The threshold effect

- When the signal to noise ratio is small, The envelope detector output does not have a component proportional to the message m(t), the noise angle is uniformly distributed from 0 to  $2\pi$
- The threshold effect is defined as the value of the carrier to noise ratio below which the noise performance of a detector deteriorates much more rapidly than proportionately to the carrier to noise ratio