

# Bandpass modulation

- **Bandpass modulation:** The process of converting a data signal to a sinusoidal waveform where its amplitude, phase or frequency, or a combination of them, are varied in accordance with the transmitting data.
- **Bandpass signal:**

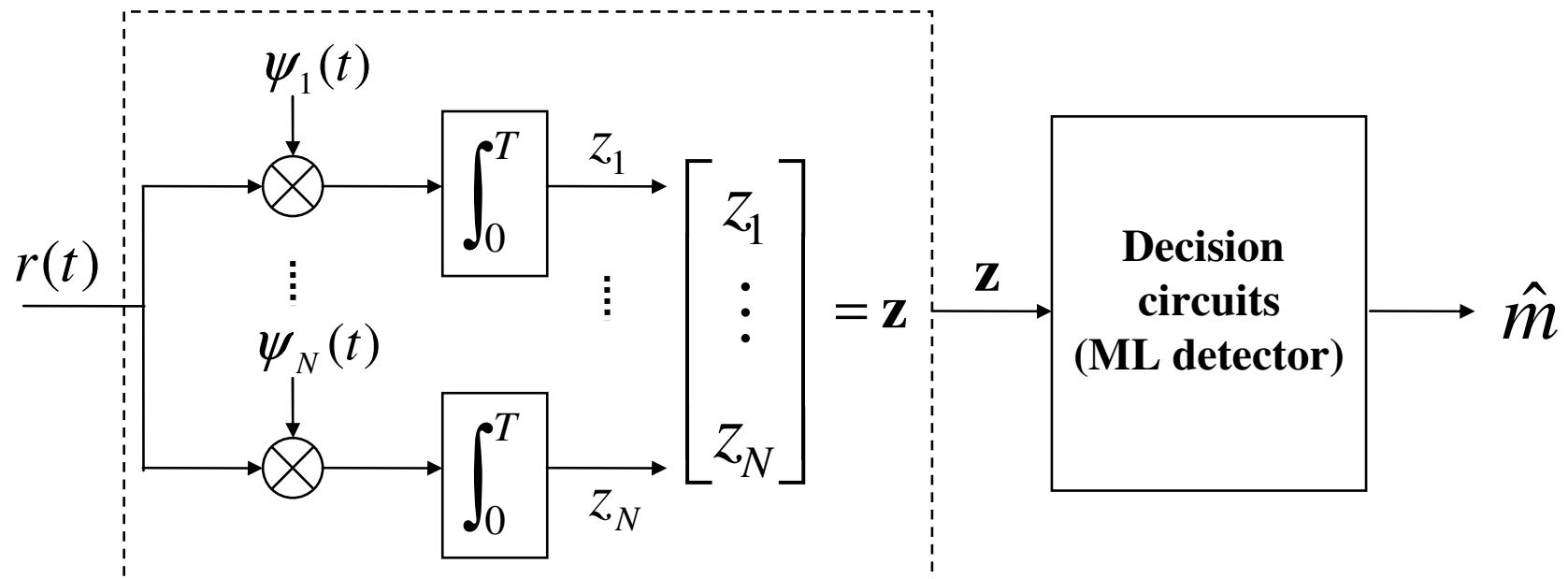
$$s_i(t) = g_T(t) \sqrt{\frac{2E_i}{T}} \cos(\omega_c t + (i-1)\Delta\omega t + \phi_i(t)) \quad 0 \leq t \leq T$$

where  $g_T(t)$  is the baseband pulse shape with energy  $E_g$ .

- We assume here (otherwise will be stated):
  - $g_T(t)$  is a rectangular pulse shape with unit energy.
  - Gray coding is used for mapping bits to symbols.
  - $E_s$  denotes average symbol energy given by  $E_s = \frac{1}{M} \sum_{i=1}^M E_{1^i}$

# Demodulation and detection

- **Demodulation:** The receiver signal is converted to baseband, filtered and sampled.
- **Detection:** Sampled values are used for detection using a decision rule such as the ML detection rule.



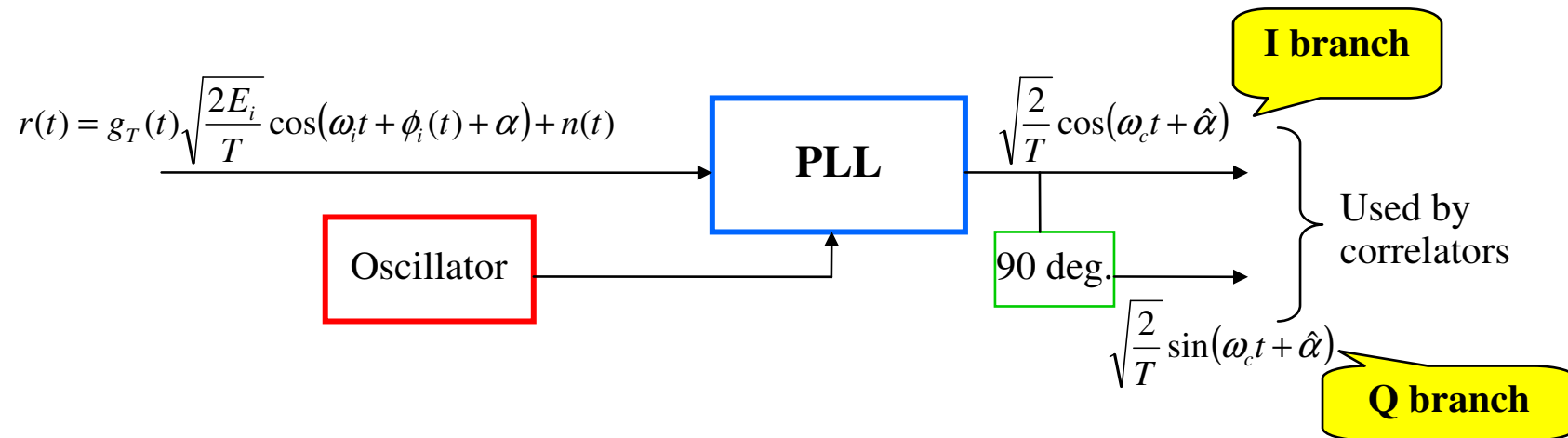
# Coherent detection

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- Coherent detection
  - requires carrier phase recovery at the receiver and hence, circuits to perform phase estimation.
  - Sources of carrier-phase mismatch at the receiver:
    - Propagation delay causes carrier-phase offset in the received signal.
    - The oscillators at the receiver which generate the carrier signal, are not usually phased locked to the transmitted carrier.

# Coherent detection ..

- Circuits such as Phase-Locked-Loop (PLL) are implemented at the receiver for carrier phase estimation ( $\alpha \approx \hat{\alpha}$ ).



# Bandpass Modulation Schemes

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- One dimensional waveforms
  - Amplitude Shift Keying (ASK)
  - M-ary Pulse Amplitude Modulation (M-PAM)
- Two dimensional waveforms
  - M-ary Phase Shift Keying (M-PSK)
  - M-ary Quadrature Amplitude Modulation (M-QAM)
- Multidimensional waveforms
  - M-ary Frequency Shift Keying (M-FSK)

# One dimensional modulation, demodulation and detection

- Amplitude Shift Keying (ASK) modulation:

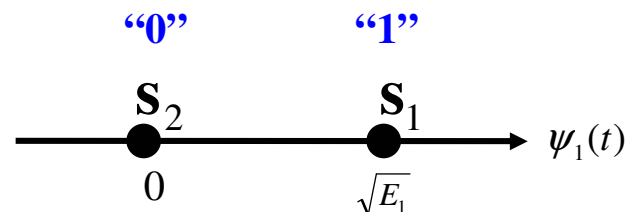
$$s_i(t) = \sqrt{\frac{2E_i}{T}} \cos(\omega_c t + \phi)$$

$$s_i(t) = a_i \psi_1(t) \quad i = 1, \dots, M$$

$$\psi_1(t) = \sqrt{\frac{2}{T}} \cos(\omega_c t + \phi)$$

$$a_i = \sqrt{E_i}$$

**On-off keying (M=2):**



# One dimensional mod.,...

## ■ M-ary Pulse Amplitude modulation (M-PAM)

$$s_i(t) = a_i \sqrt{\frac{2}{T}} \cos(\omega_c t)$$

$$s_i(t) = a_i \psi_1(t) \quad i = 1, \dots, M$$

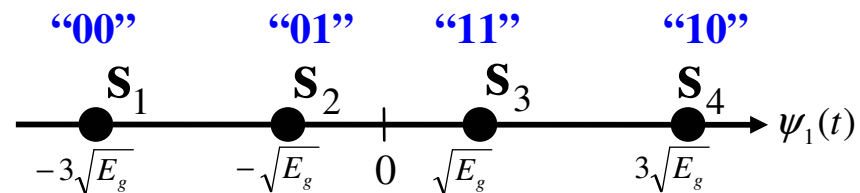
$$\psi_1(t) = \sqrt{\frac{2}{T}} \cos(\omega_c t)$$

$$a_i = (2i - 1 - M) \sqrt{E_g}$$

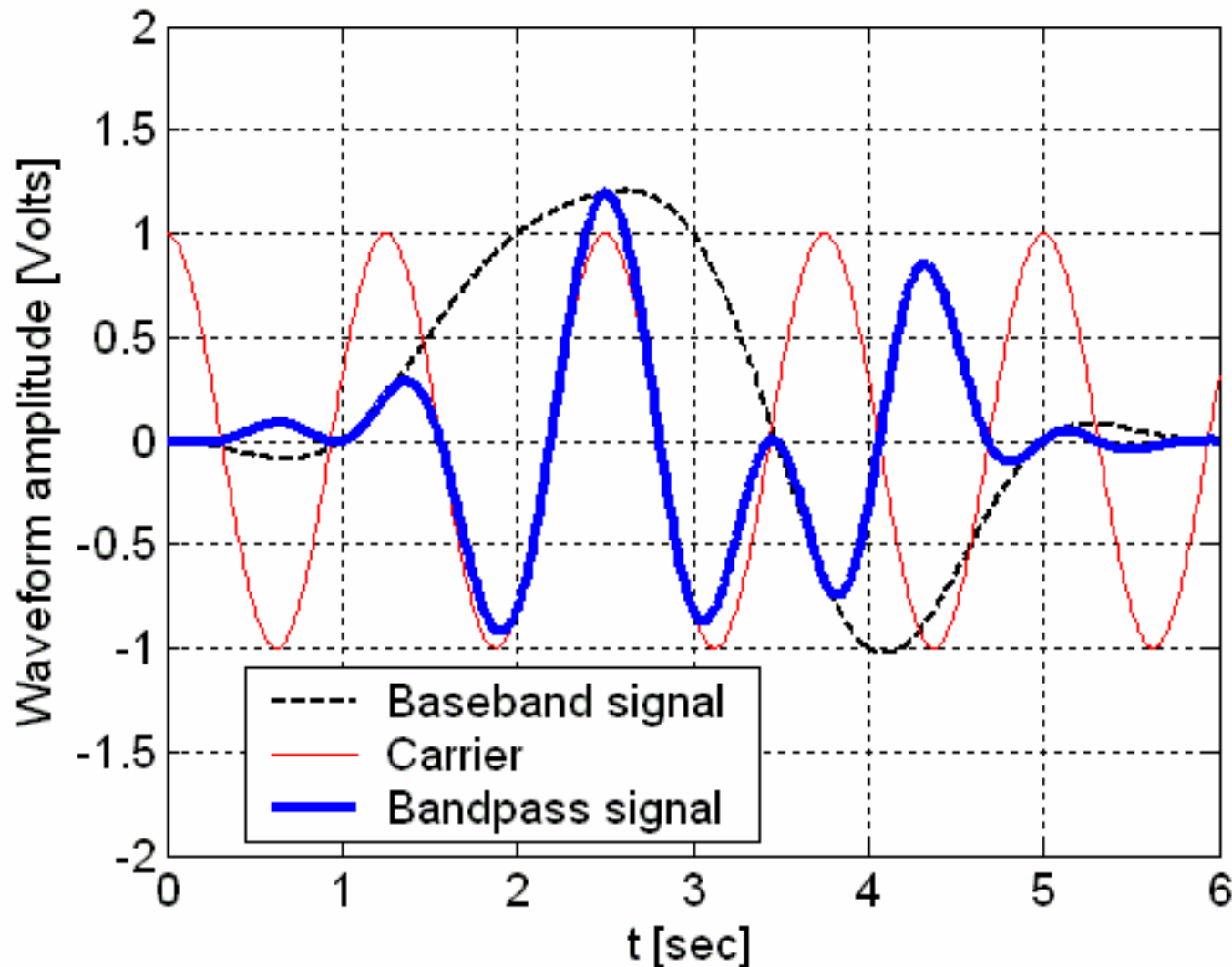
$$E_i = \|\mathbf{s}_i\|^2 = E_g (2i - 1 - M)^2$$

$$E_s = \frac{(M^2 - 1)}{3} E_g$$

### 4-PAM:



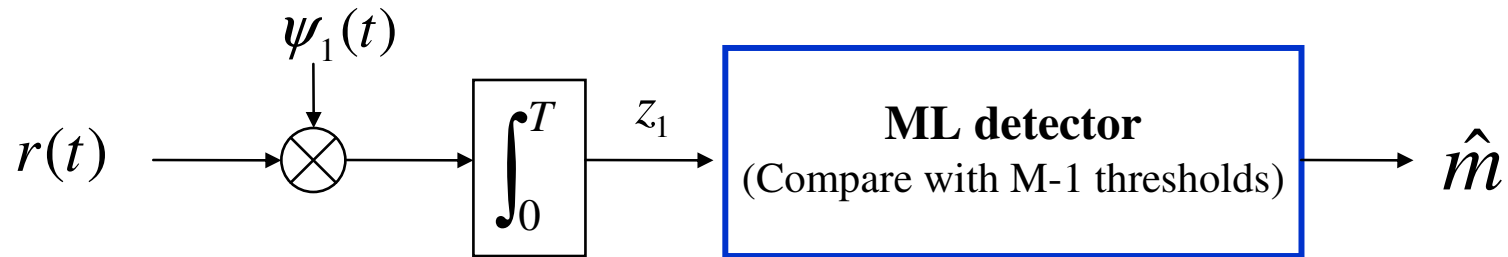
# Example of bandpass modulation: Binary PAM





# One dimensional mod.,...-cont'd

- Coherent detection of M-PAM



# Two dimensional modulation, demodulation and detection (M-PSK)

## ■ M-ary Phase Shift Keying (M-PSK)

$$s_i(t) = \sqrt{\frac{2E_s}{T}} \cos\left(\omega_c t + \frac{2\pi i}{M}\right)$$

$$s_i(t) = a_{i1}\psi_1(t) + a_{i2}\psi_2(t) \quad i = 1, \dots, M$$

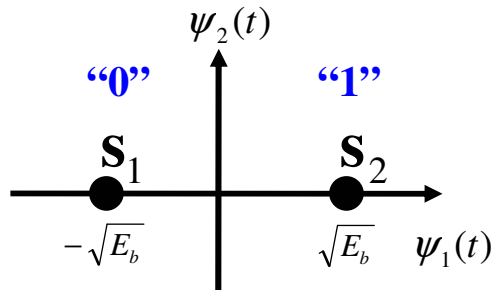
$$\psi_1(t) = \sqrt{\frac{2}{T}} \cos(\omega_c t) \quad \psi_2(t) = -\sqrt{\frac{2}{T}} \sin(\omega_c t)$$

$$a_{i1} = \sqrt{E_s} \cos\left(\frac{2\pi i}{M}\right) \quad a_{i2} = \sqrt{E_s} \sin\left(\frac{2\pi i}{M}\right)$$

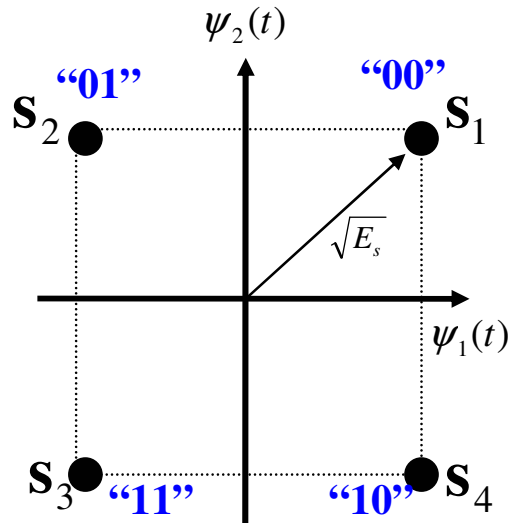
$$E_s = E_i = \|\mathbf{s}_i\|^2$$

# Two dimensional mod.,... (MPSK)

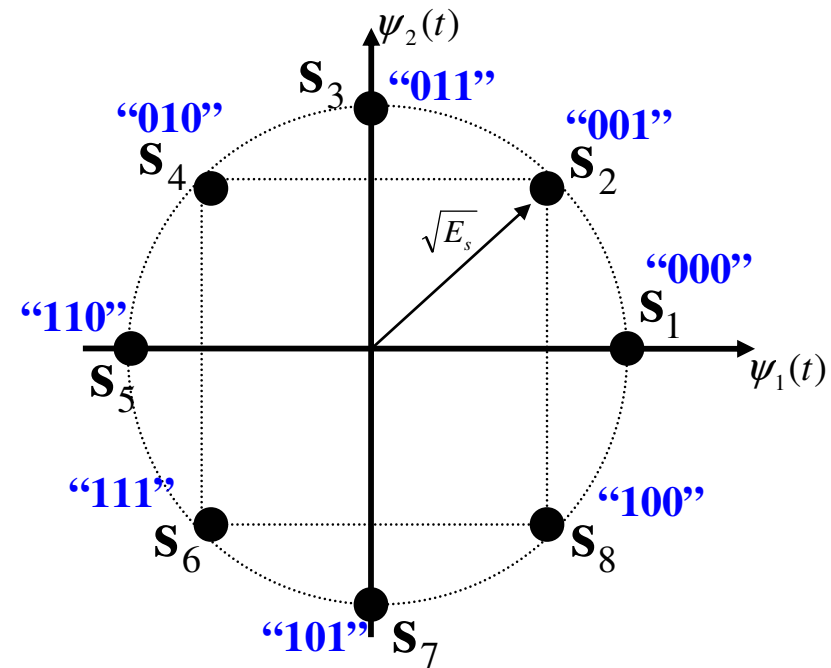
## BPSK (M=2)



## QPSK (M=4)

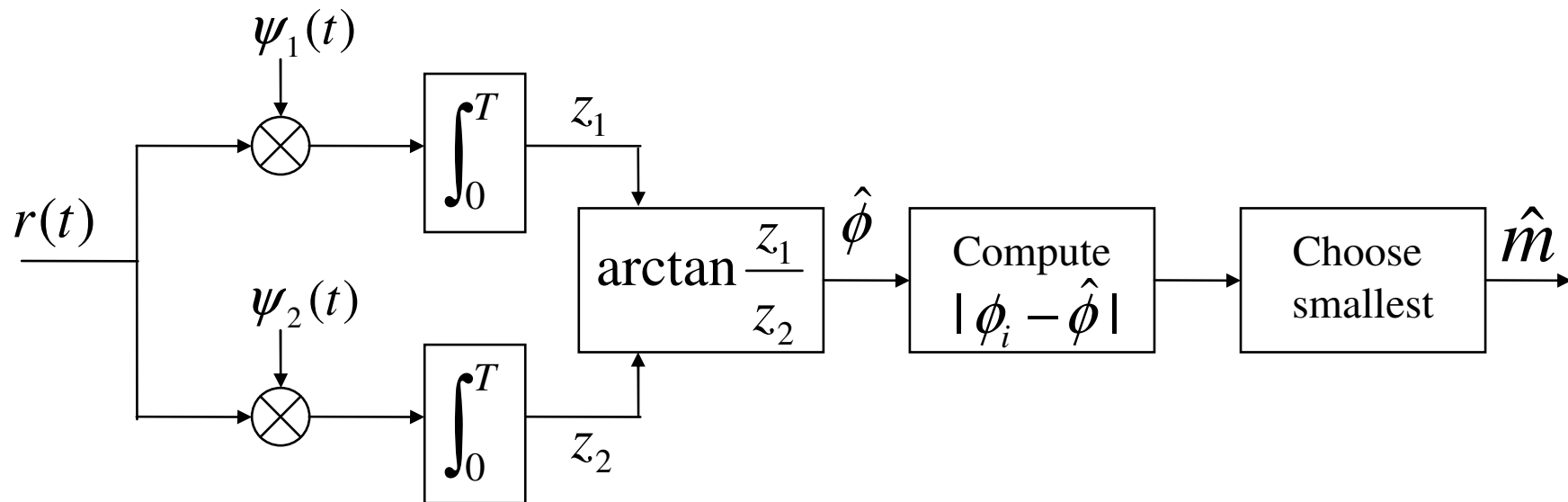


## 8PSK (M=8)



# Two dimensional mod.,... (MPSK)

- Coherent detection of MPSK



# Two dimensional mod.,... (M-QAM)

## ■ M-ary Quadrature Amplitude Mod. (M-QAM)

$$s_i(t) = \sqrt{\frac{2E_i}{T}} \cos(\omega_c t + \varphi_i)$$

$$s_i(t) = a_{i1}\psi_1(t) + a_{i2}\psi_2(t) \quad i = 1, \dots, M$$

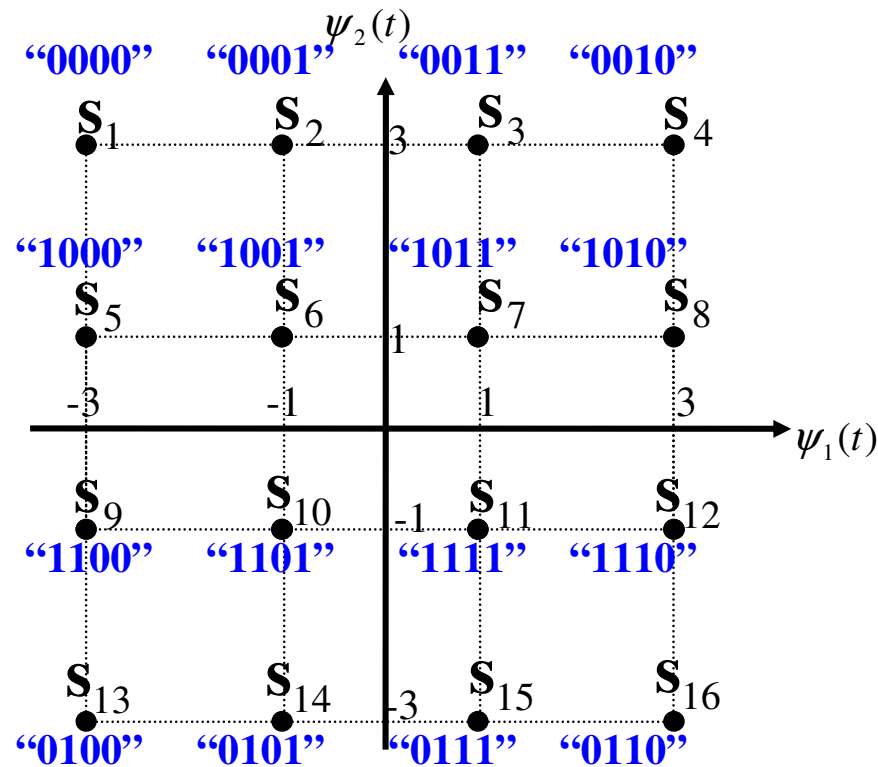
$$\psi_1(t) = \sqrt{\frac{2}{T}} \cos(\omega_c t) \quad \psi_2(t) = \sqrt{\frac{2}{T}} \sin(\omega_c t)$$

where  $a_{i1}$  and  $a_{i2}$  are PAM symbols and  $E_s = \frac{2(M-1)}{3}$

$$(a_{i1}, a_{i2}) = \begin{bmatrix} (-\sqrt{M} + 1, \sqrt{M} - 1) & (-\sqrt{M} + 3, \sqrt{M} - 1) & \cdots & (\sqrt{M} - 1, \sqrt{M} - 1) \\ (-\sqrt{M} + 1, \sqrt{M} - 3) & (-\sqrt{M} + 3, \sqrt{M} - 3) & \cdots & (\sqrt{M} - 1, \sqrt{M} - 3) \\ \vdots & \vdots & \vdots & \vdots \\ (-\sqrt{M} + 1, -\sqrt{M} + 1) & (-\sqrt{M} + 3, -\sqrt{M} + 1) & \cdots & (\sqrt{M} - 1, -\sqrt{M} + 1) \end{bmatrix}$$

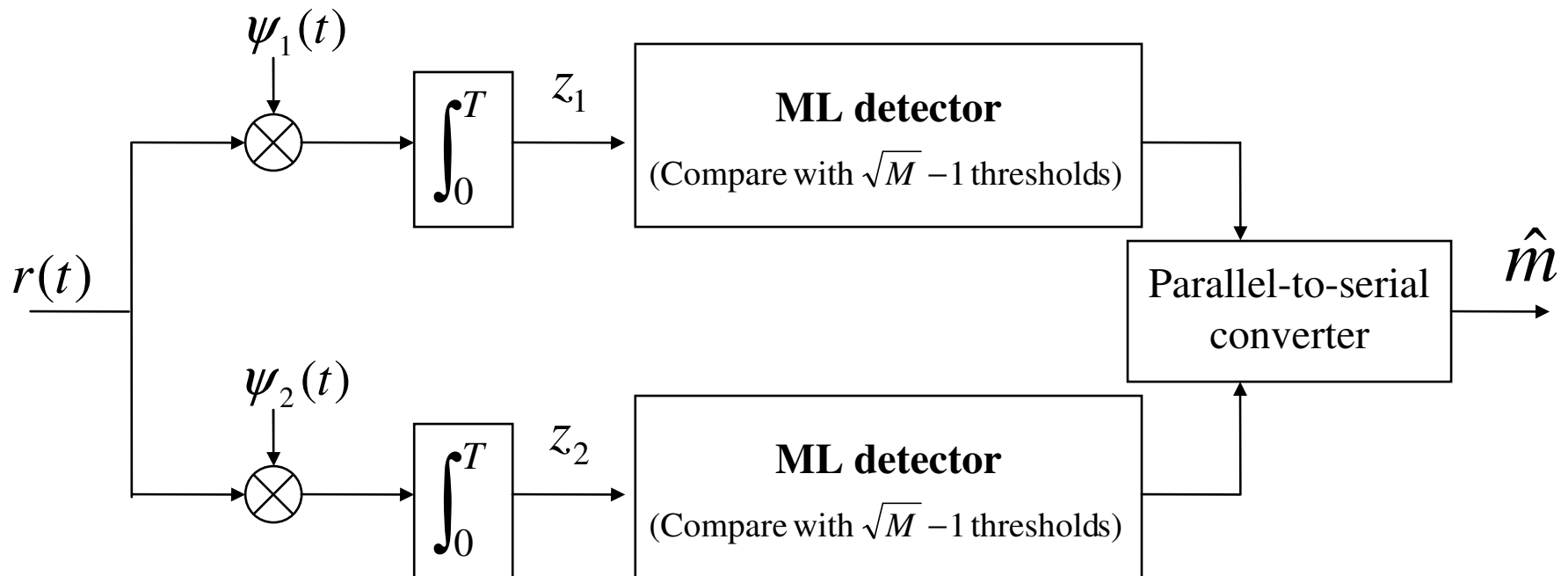
# Two dimensional mod.,... (M-QAM)

## 16-QAM



# Two dimensional mod.,... (M-QAM)

## ■ Coherent detection of M-QAM



# Multi-dimensional modulation, demodulation & detection

## ■ M-ary Frequency Shift keying (M-FSK)

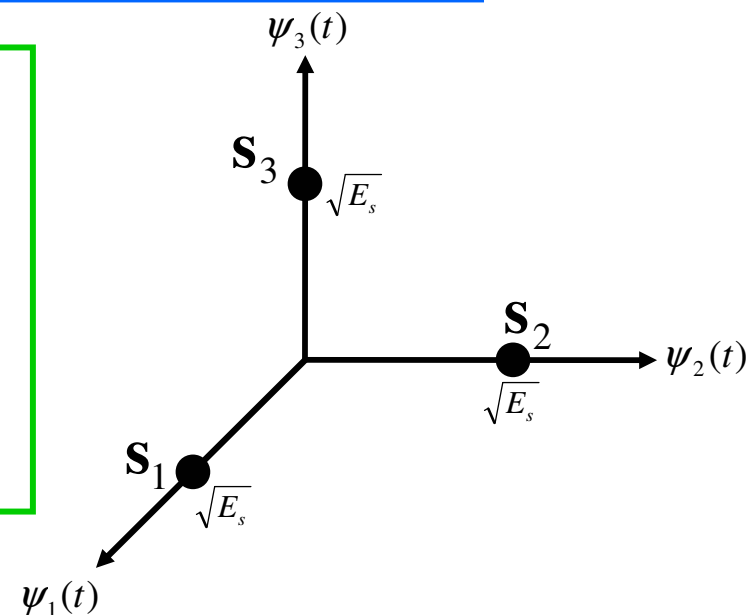
$$s_i(t) = \sqrt{\frac{2E_s}{T}} \cos(\omega_i t) = \sqrt{\frac{2E_s}{T}} \cos(\omega_c t + (i-1)\Delta\omega t)$$

$$\Delta f = \frac{\Delta\omega}{2\pi} = \frac{1}{2T}$$

$$s_i(t) = \sum_{j=1}^M a_{ij} \psi_j(t) \quad i = 1, \dots, M$$

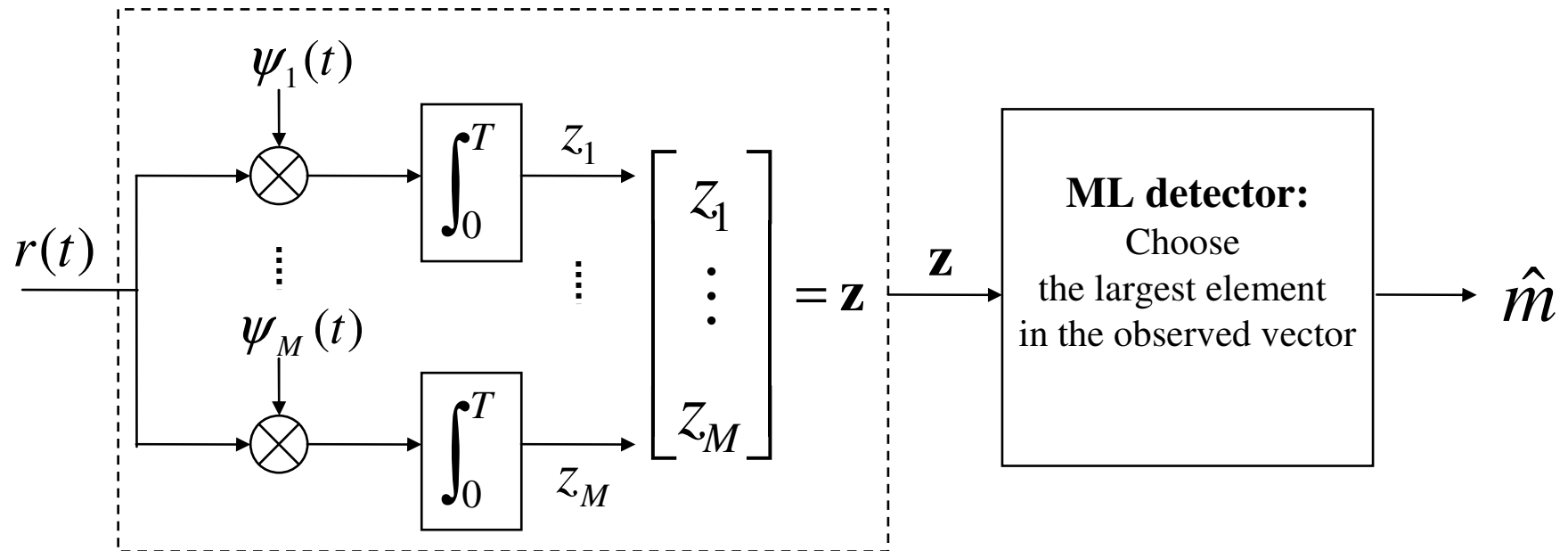
$$\psi_i(t) = \sqrt{\frac{2}{T}} \cos(\omega_i t) \quad a_{ij} = \begin{cases} \sqrt{E_s} & i = j \\ 0 & i \neq j \end{cases}$$

$$E_s = E_i = \|\mathbf{s}_i\|^2$$





# Multi-dimensional mod.,... (M-FSK)



# Non-coherent detection

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- Non-coherent detection:
  - *No need for a reference in phase* with the received carrier
  - *Less complexity* compared to coherent detection at the price of *higher error rate*.

# Non-coherent detection ...

## ■ Differential coherent detection

### ■ Differential encoding of the message

- The symbol phase changes if the current bit is different from the previous bit.

$$s_i(t) = \sqrt{\frac{2E}{T}} \cos(\omega_0 t + \theta_i(t)), \quad 0 \leq t \leq T, \quad i = 1, \dots, M$$

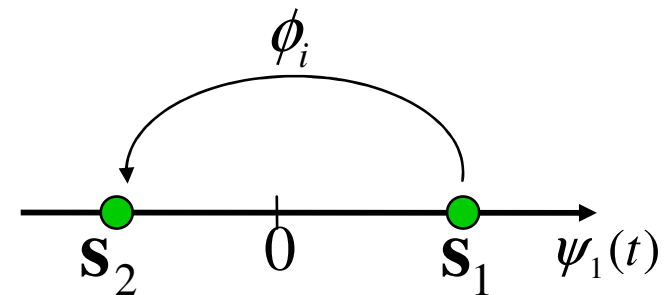
$$\theta_k(nT) = \theta_k((n-1)T) + \phi_i(nT)$$

Symbol index:  $k$

Data bits:  $m_k$

Symbol phase:  $\theta_k$

	0	1	2	3	4	5	6	7
	1	1	0	1	0	1	1	
	$\pi$	$\pi$	$\pi$	0	$\pi$	0	$\pi$	$\pi$

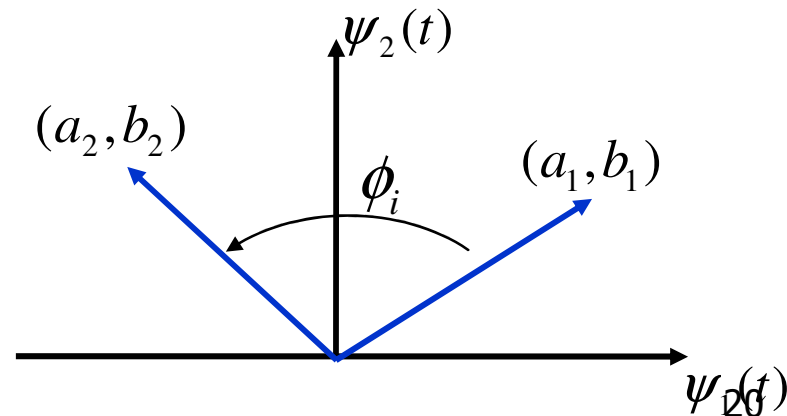


# Non-coherent detection ...

- Coherent detection for diff encoded mod.
  - assumes slow variation in carrier-phase mismatch during two symbol intervals.
  - correlates the received signal with basis functions
  - uses the phase difference between the current received vector and previously estimated symbol

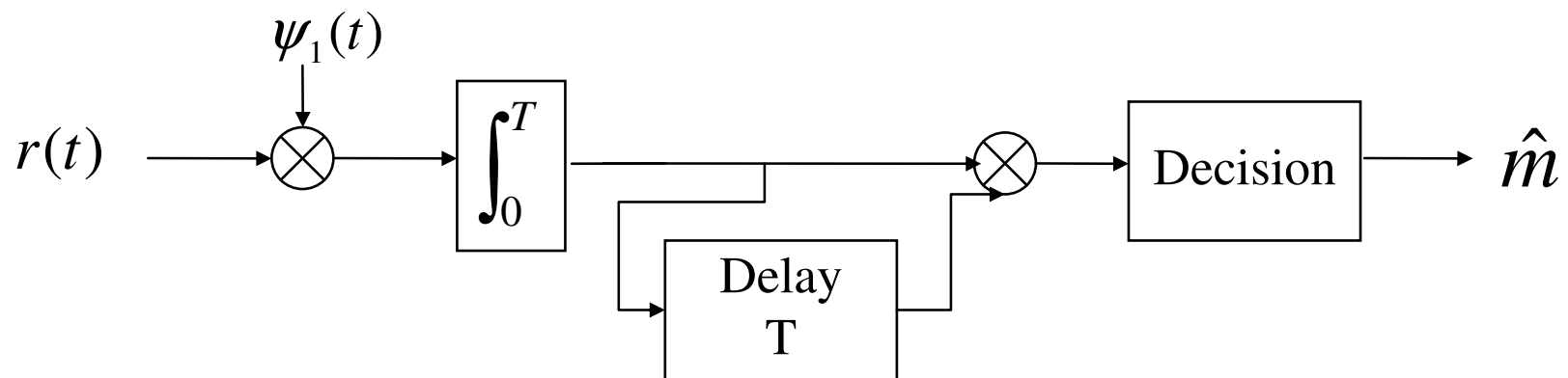
$$r(t) = \sqrt{\frac{2E}{T}} \cos(\omega_0 t + \theta_i(t) + \alpha) + n(t), \quad 0 \leq t \leq T$$

$$(\theta_i(nT) + \alpha) - (\theta_j((n-1)T) + \alpha) = \theta_i(nT) - \theta_j((n-1)T) = \phi_i(nT)$$



# Non-coherent detection ...

- Optimum differentially coherent detector



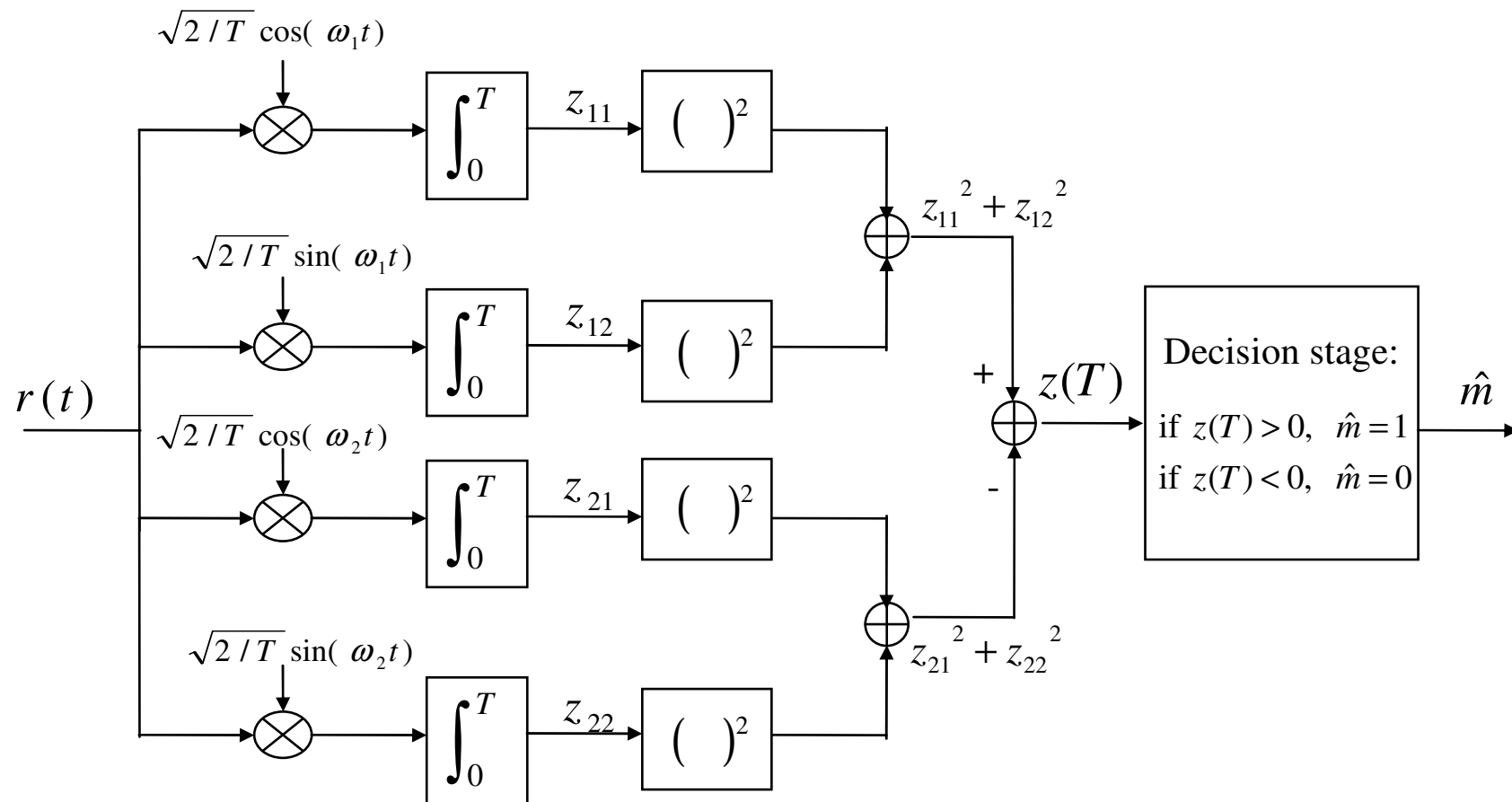
# Non-coherent detection ...

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- Energy detection
  - Non-coherent detection for orthogonal signals (e.g. M-FSK)
    - Carrier-phase offset causes partial correlation between I and Q branches for each candidate signal.
    - The received energy corresponding to each candidate signal is used for detection.

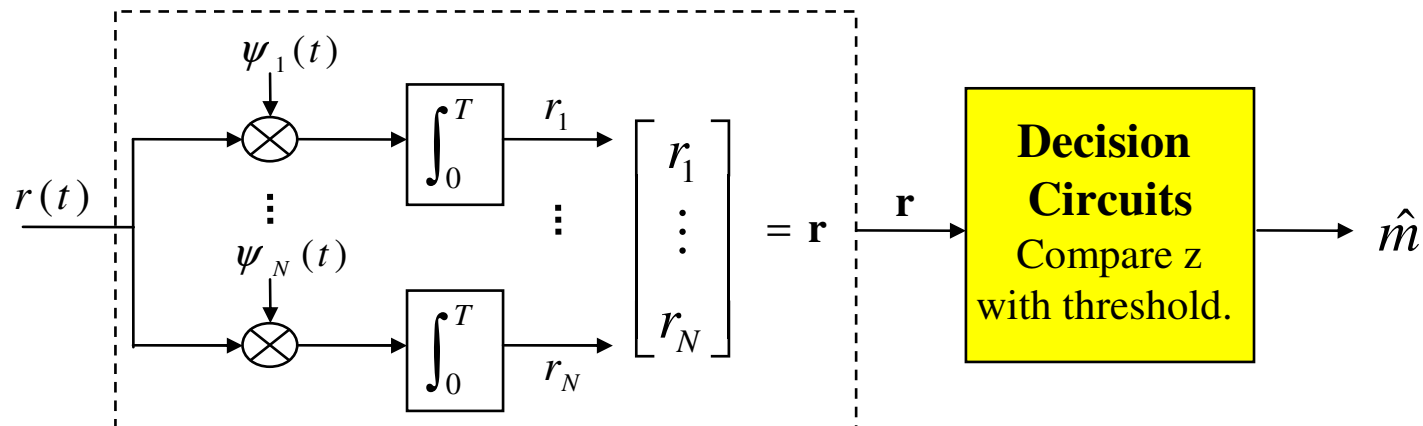
# Non-coherent detection ...

## ■ Non-coherent detection of BFSK



# Error probability of bandpass modulation

- Before evaluating the error probability, it is important to remember that:
  - The type of modulation and detection (coherent or non-coherent) determines the structure of the decision circuits and hence the decision variable, denoted by  $z$ .
  - The decision variable,  $z$ , is compared with  $M-1$  thresholds, corresponding to  $M$  decision regions for detection purposes.





# Error probability ...

- The matched filters output (observation vector =  $\mathbf{r}$ ) is the detector input and the decision variable is a  $z = f(\mathbf{r})$  function of  $\mathbf{r}$ , i.e.
  - For MPAM, MQAM and MFSK with coherent detection  $z = \mathbf{r}$
  - For MPSK with coherent detection  $z = \angle \mathbf{r}$
  - For non-coherent detection (M-FSK and DPSK),  $z = |\mathbf{r}|$
- We know that for calculating the average probability of symbol error, we need to determine

$$\Pr(\mathbf{r} \text{ lies inside } Z_1 | s_i \text{ sent}) \equiv \Pr(z \text{ satisfies condition } C_1 | s_i \text{ sent})$$

- *Hence, we need to know the statistics of  $z$ , which depends on the modulation scheme and the detection type.*

# Error probability ...

## ■ AWGN channel model: $\mathbf{r} = \mathbf{s}_i + \mathbf{n}$

- The signal vector  $\mathbf{s}_i = (a_{i1}, a_{i2}, \dots, a_{iN})$  is deterministic.
- The elements of the noise vector  $\mathbf{n} = (n_1, n_2, \dots, n_N)$  are i.i.d Gaussian random variables with zero-mean and variance  $N_0/2$ . The noise vector's pdf is

$$p_{\mathbf{n}}(\mathbf{n}) = \frac{1}{(\pi N_0)^{N/2}} \exp\left(-\frac{\|\mathbf{n}\|^2}{N_0}\right)$$

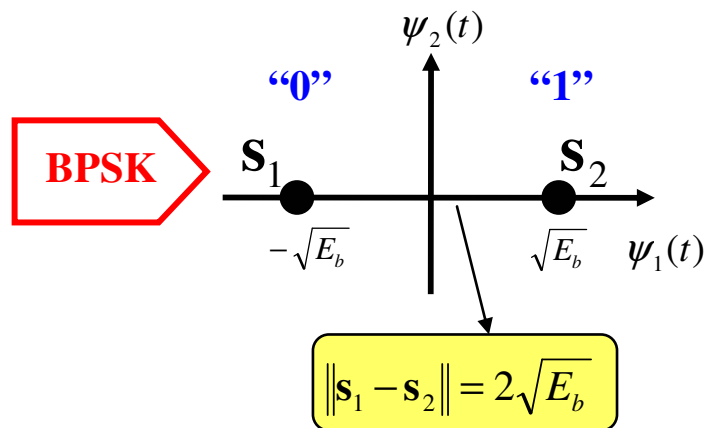
- The elements of the observed vector  $\mathbf{r} = (r_1, r_2, \dots, r_N)$  are independent Gaussian random variables. Its pdf is

$$p_{\mathbf{r}}(\mathbf{r} | \mathbf{s}_i) = \frac{1}{(\pi N_0)^{N/2}} \exp\left(-\frac{\|\mathbf{r} - \mathbf{s}_i\|^2}{N_0}\right)$$

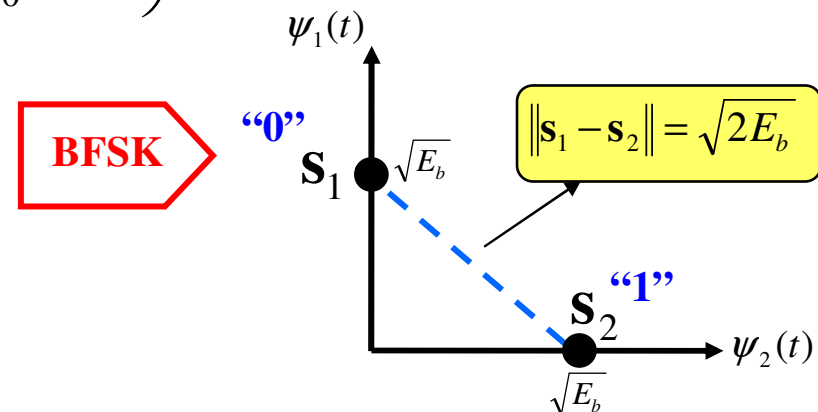
# Error probability ...

- BPSK and BFSK with *coherent* detection:

$$P_B = Q\left(\frac{\|\mathbf{s}_1 - \mathbf{s}_2\|/2}{\sqrt{N_0/2}}\right)$$



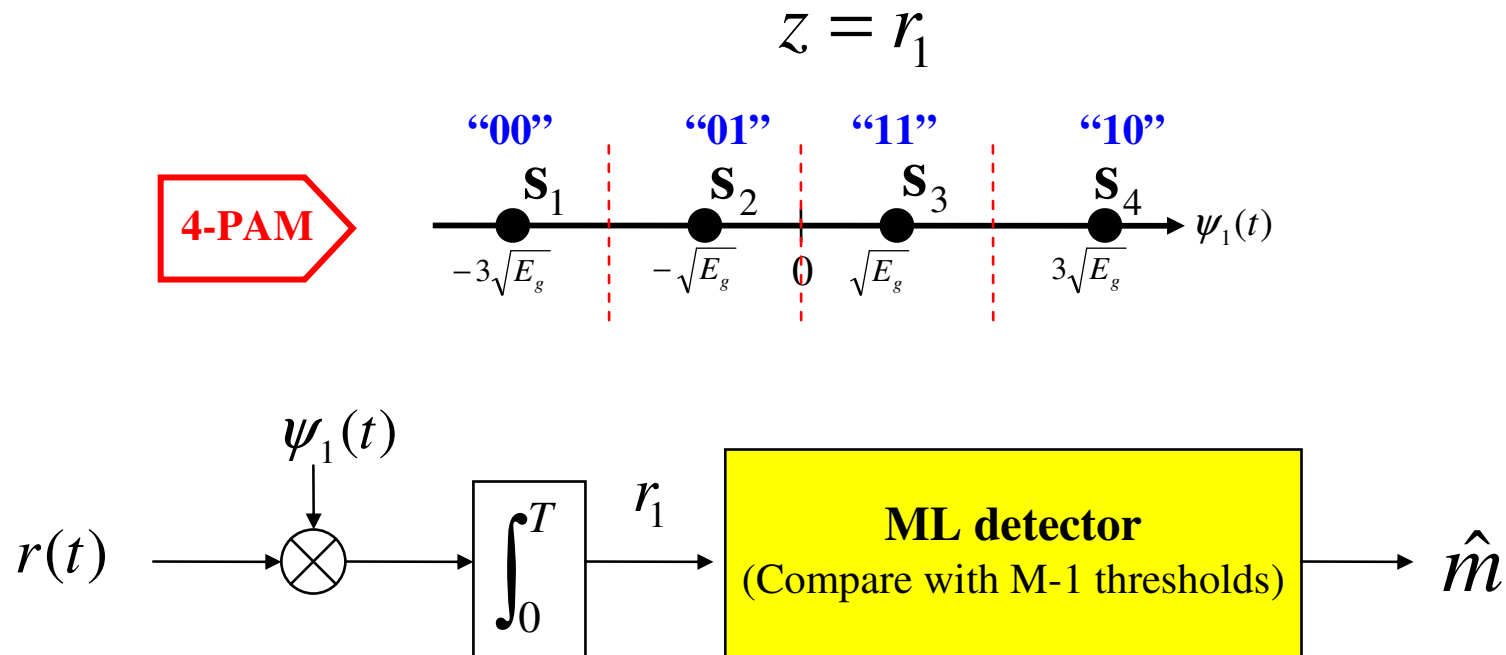
$$P_B = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$



$$P_B = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$$

# Error probability ....

- *Coherent* detection of M-PAM
  - Decision variable:



# Error probability ....

## ■ Coherent detection of M-PAM ....

- Error happens if the noise,  $n_1 = r_1 - s_m$ , exceeds in amplitude one-half of the distance between adjacent symbols. For symbols on the border, error can happen only in one direction. Hence:

$$P_e(\mathbf{s}_m) = \Pr(|n_1| = |r_1 - s_m| > \sqrt{E_g}) \text{ for } 2 < m < M - 1;$$

$$P_e(\mathbf{s}_1) = \Pr(n_1 = r_1 - s_1 > \sqrt{E_g}) \quad \text{and} \quad P_e(\mathbf{s}_M) = \Pr(n_1 = r_1 - s_M < -\sqrt{E_g})$$

$$\begin{aligned} P_E(M) &= \frac{1}{M} \sum_{m=1}^M P_e(\mathbf{s}_m) = \frac{M-2}{M} \Pr(|n_1| > \sqrt{E_g}) + \frac{1}{M} \Pr(n_1 > \sqrt{E_g}) + \frac{1}{M} \Pr(n_1 < -\sqrt{E_g}) \\ &= \frac{2(M-1)}{M} \Pr(n_1 > \sqrt{E_g}) = \frac{2(M-1)}{M} \int_{\sqrt{E_g}}^{\infty} p_{n_1}(n) dn = \frac{2(M-1)}{M} Q\left(\sqrt{\frac{2E_g}{N_0}}\right) \end{aligned}$$

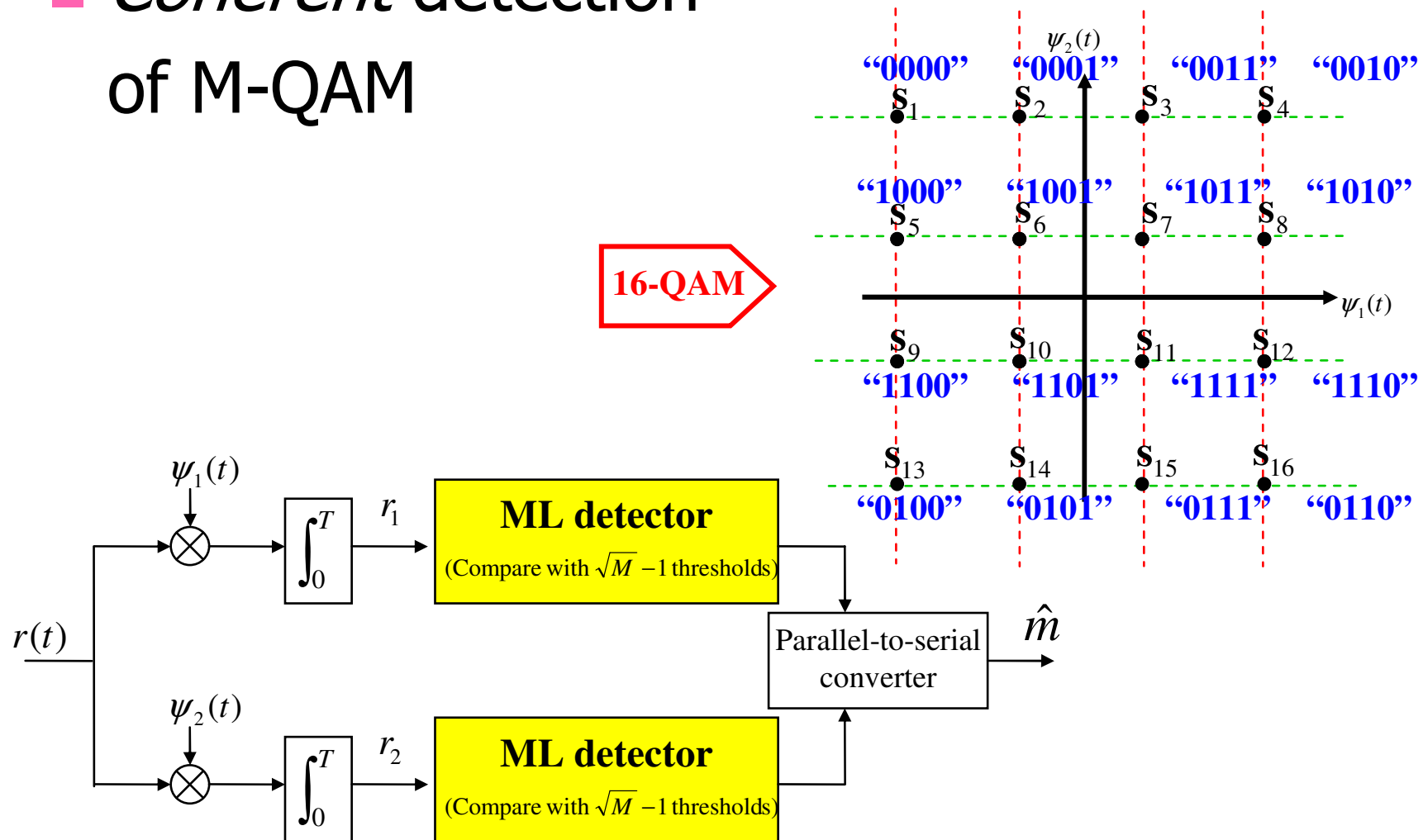
$$E_s = (\log_2 M) E_b = \frac{(M^2 - 1)}{3} E_g$$

$$P_E(M) = \frac{2(M-1)}{M} Q\left(\sqrt{\frac{6 \log_2 M}{M^2 - 1} \frac{E_b}{N_0}}\right)$$

Gaussian pdf with zero mean and variance  $N_0/2$

# Error probability ...

- *Coherent* detection of M-QAM



# Error probability ...

- *Coherent* detection of M-QAM ...
- M-QAM can be viewed as the combination of two  $\sqrt{M}$  - PAM modulations on I and Q branches, respectively.
- No error occurs if no error is detected on either the I or the Q branch.
- Considering the symmetry of the signal space and the orthogonality of the I and Q branches:

$$P_E(M) = 1 - P_C(M) = 1 - \Pr(\text{no error detected on I and Q branches})$$

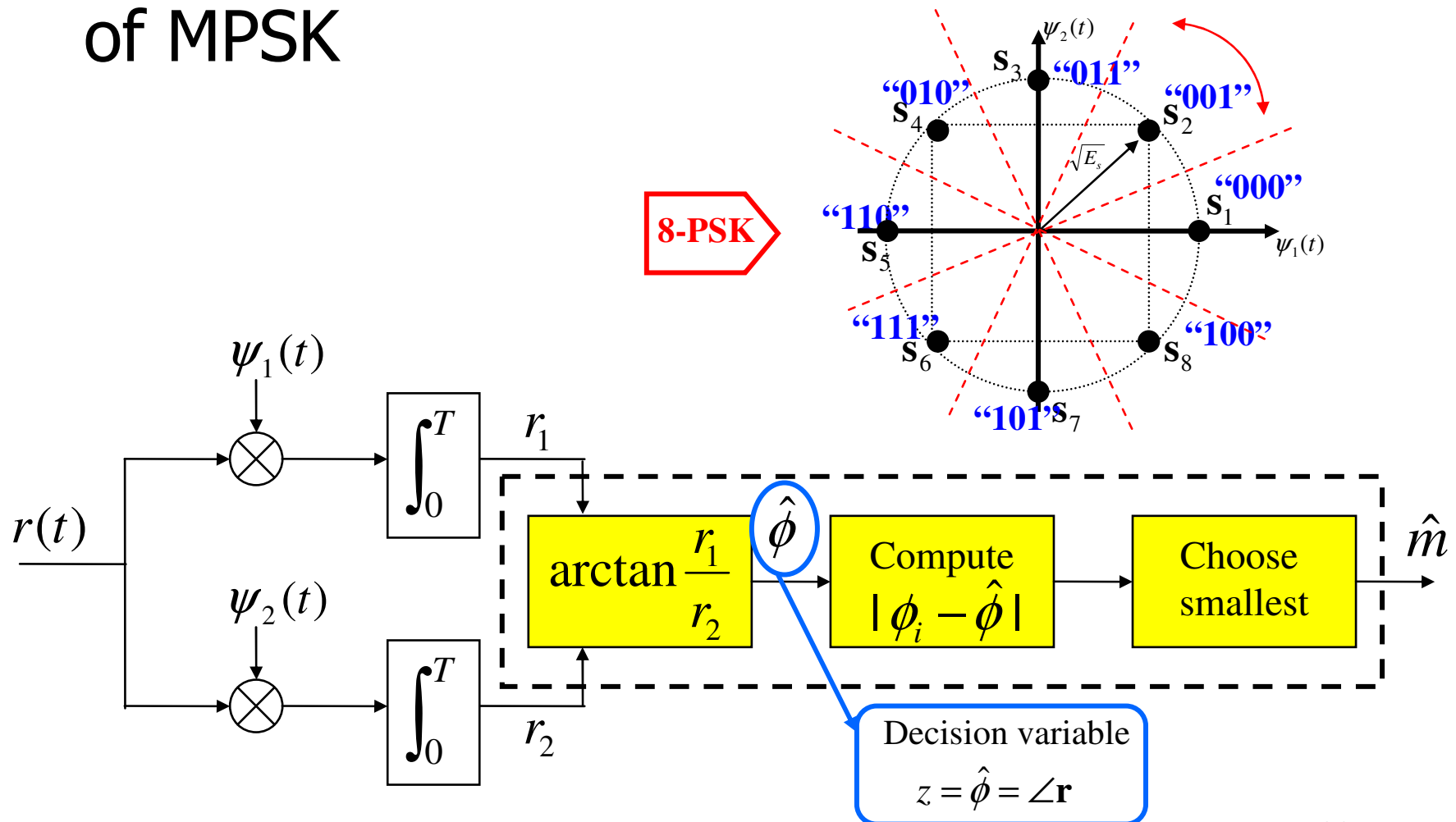
$$\begin{aligned} \Pr(\text{no error detected on I and Q branches}) &= \Pr(\text{no error on I})\Pr(\text{no error on Q}) \\ &= \Pr(\text{no error on I})^2 = \left(1 - P_E(\sqrt{M})\right)^2 \end{aligned}$$

$$P_E(M) = 4 \left(1 - \frac{1}{\sqrt{M}}\right) Q \left( \sqrt{\frac{3 \log_2 M}{M-1} \frac{E_b}{N_0}} \right)$$

Average probability of symbol error for  $\sqrt{M}$  - PAM

# Error probability ...

- *Coherent* detection of MPSK





# Error probability ...

## ■ Coherent detection of MPSK ...

- The detector compares the phase of observation vector to M-1 thresholds.
- Due to the circular symmetry of the signal space, we have:

$$P_E(M) = 1 - P_C(M) = 1 - \frac{1}{M} \sum_{m=1}^M P_c(\mathbf{s}_m) = 1 - P_c(\mathbf{s}_1) = 1 - \int_{-\pi/M}^{\pi/M} p_{\hat{\phi}}(\phi) d\phi$$

where

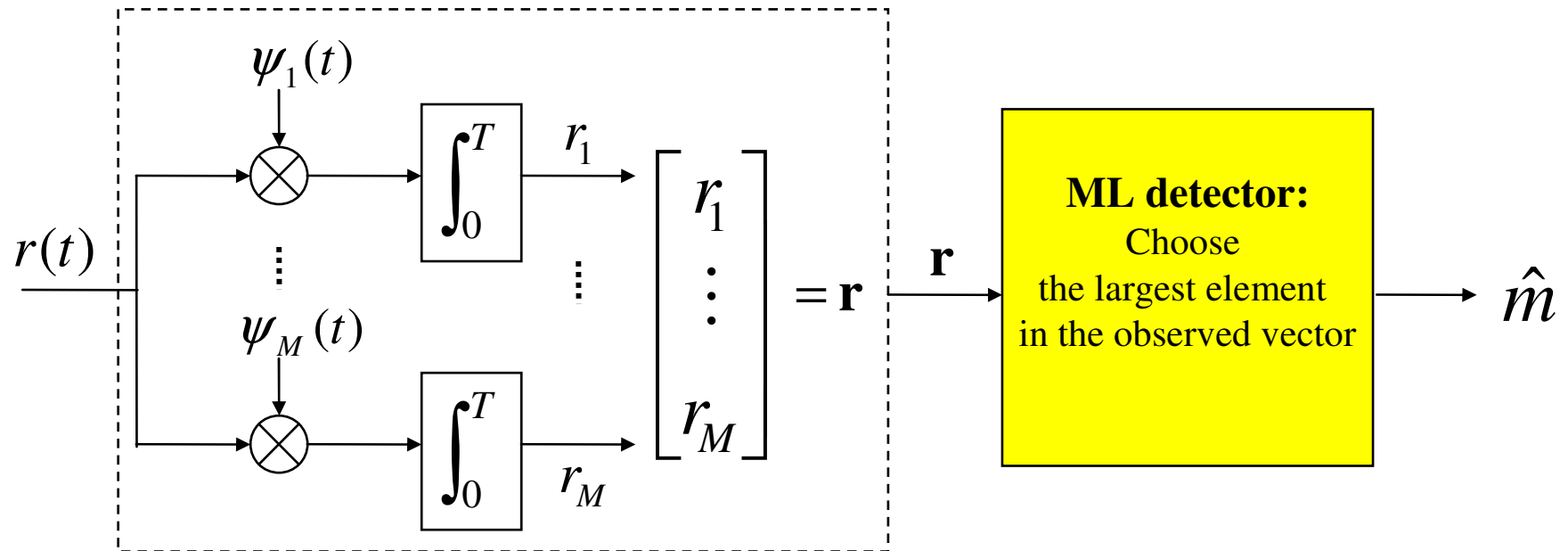
$$p_{\hat{\phi}}(\phi) \approx \sqrt{\frac{2 E_s}{\pi N_0}} \cos(\phi) \exp\left(-\frac{E_s}{N_0} \sin^2 \phi\right); \quad |\phi| \leq \frac{\pi}{2}$$

- It can be shown that

$$P_E(M) \approx 2Q\left(\sqrt{\frac{2E_s}{N_0}} \sin\left(\frac{\pi}{M}\right)\right) \quad \text{or} \quad P_E(M) \approx 2Q\left(\sqrt{\frac{2(\log_2 M)E_b}{N_0}} \sin\left(\frac{\pi}{M}\right)\right)$$

# Error probability ...

- *Coherent* detection of M-FSK



# Error probability ...

- *Coherent* detection of M-FSK ...
- The dimension of the signal space is  $M$ . An upper bound for the average symbol error probability can be obtained by using the union bound. Hence:

$$P_E(M) \leq (M-1)Q\left(\sqrt{\frac{E_s}{N_0}}\right)$$

or, equivalently

$$P_E(M) \leq (M-1)Q\left(\sqrt{\frac{(\log_2 M)E_b}{N_0}}\right)$$

# Bit error probability versus symbol error probability

- Number of bits per symbol  $k = \log_2 M$
- For orthogonal M-ary signaling (M-FSK)

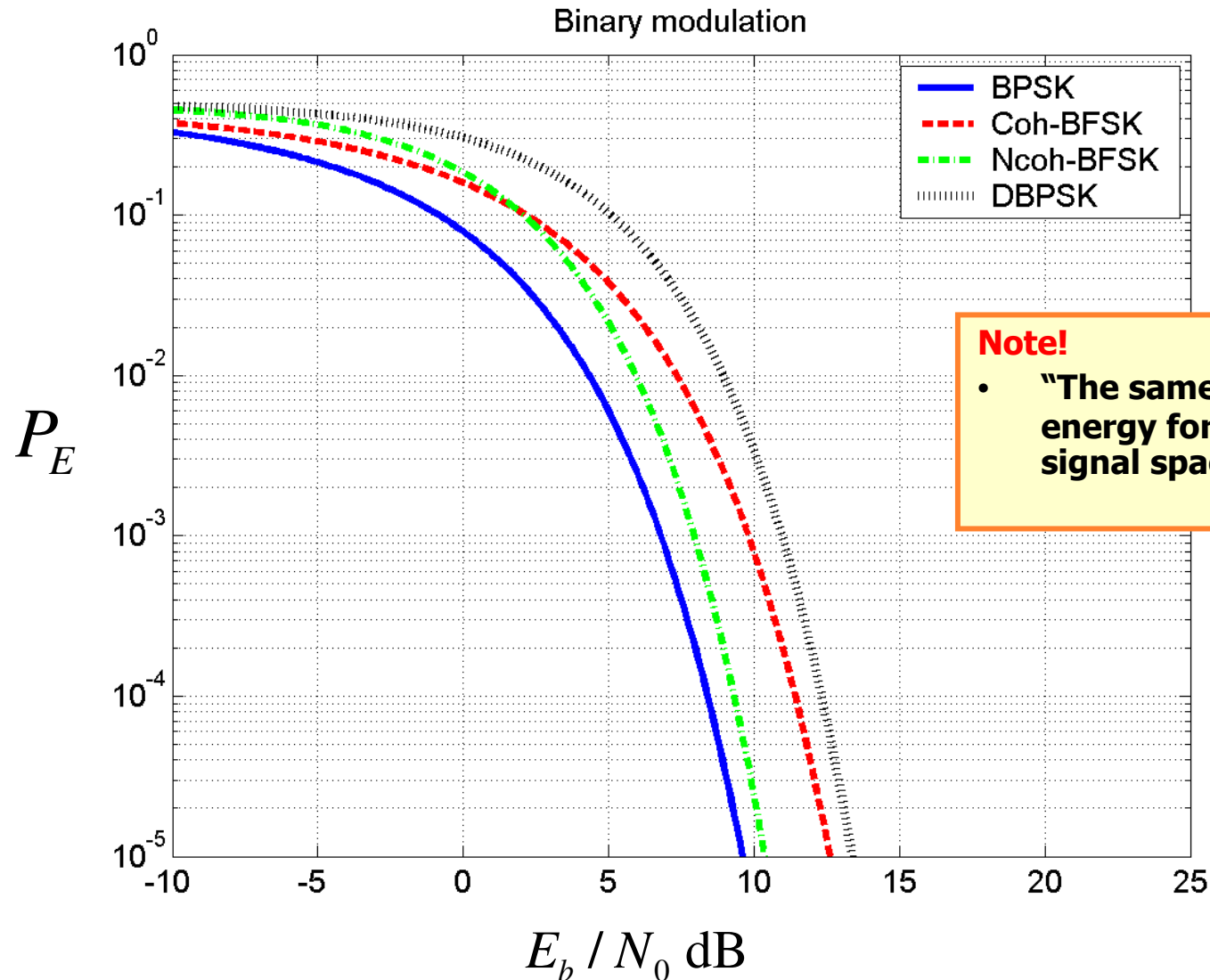
$$\frac{P_B}{P_E} = \frac{2^{k-1}}{2^k - 1} = \frac{M/2}{M-1}$$

$$\lim_{k \rightarrow \infty} \frac{P_B}{P_E} = \frac{1}{2}$$

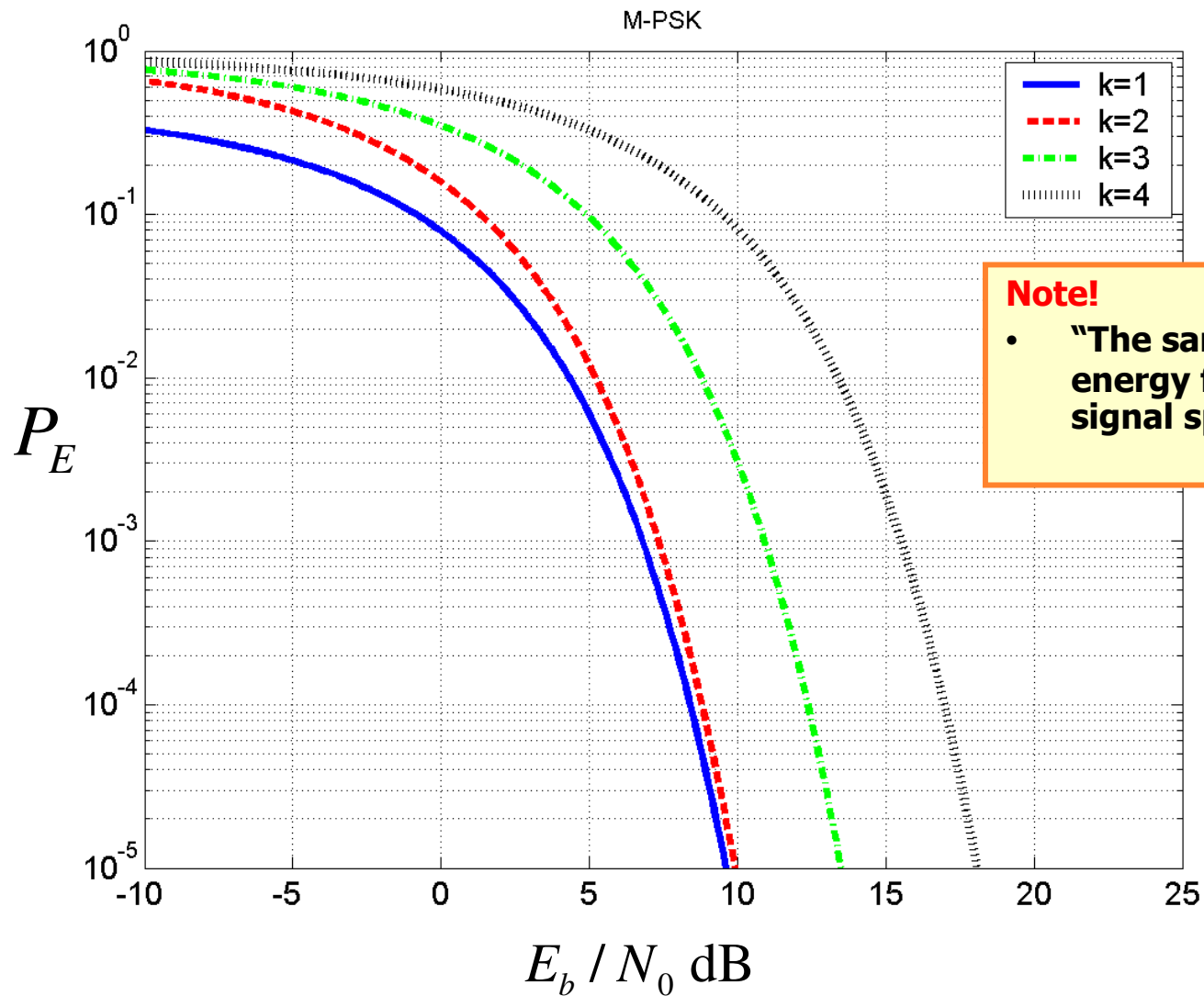
- For M-PSK, M-PAM and M-QAM

$$P_B \approx \frac{P_E}{k} \text{ for } P_E \ll 1$$

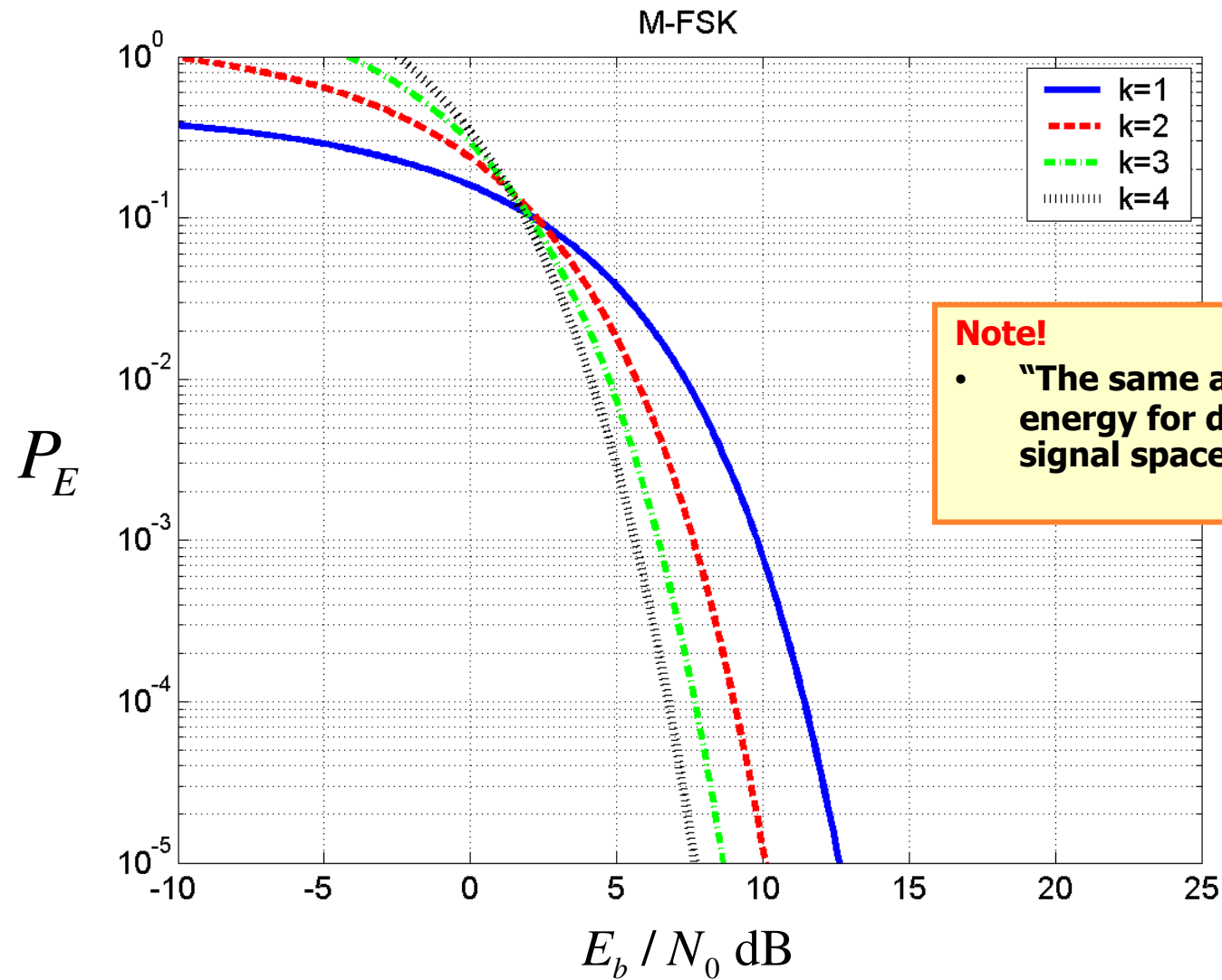
# Probability of symbol error for binary modulation



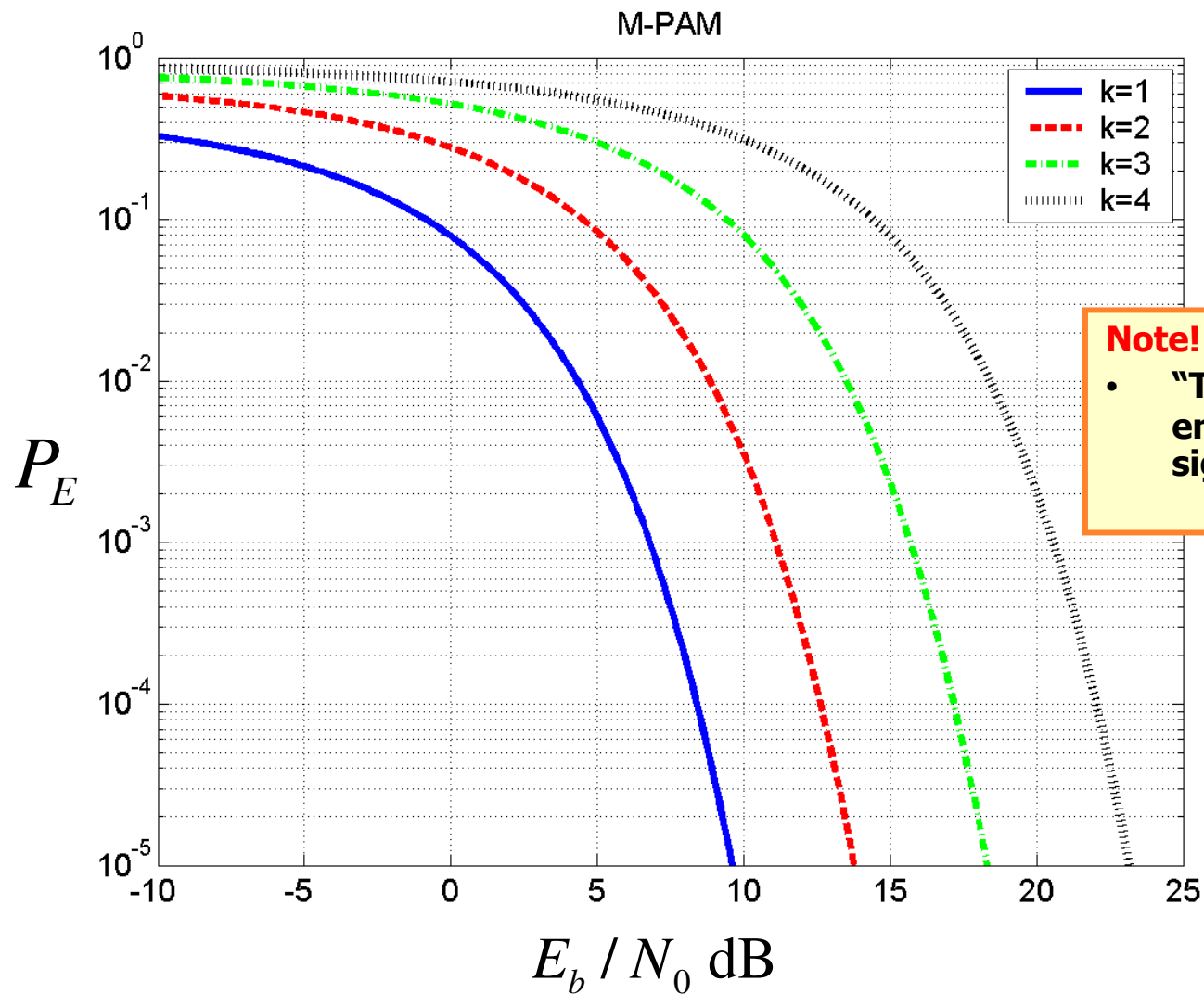
# Probability of symbol error for M-PSK



# Probability of symbol error for M-FSK



# Probability of symbol error for M-PAM

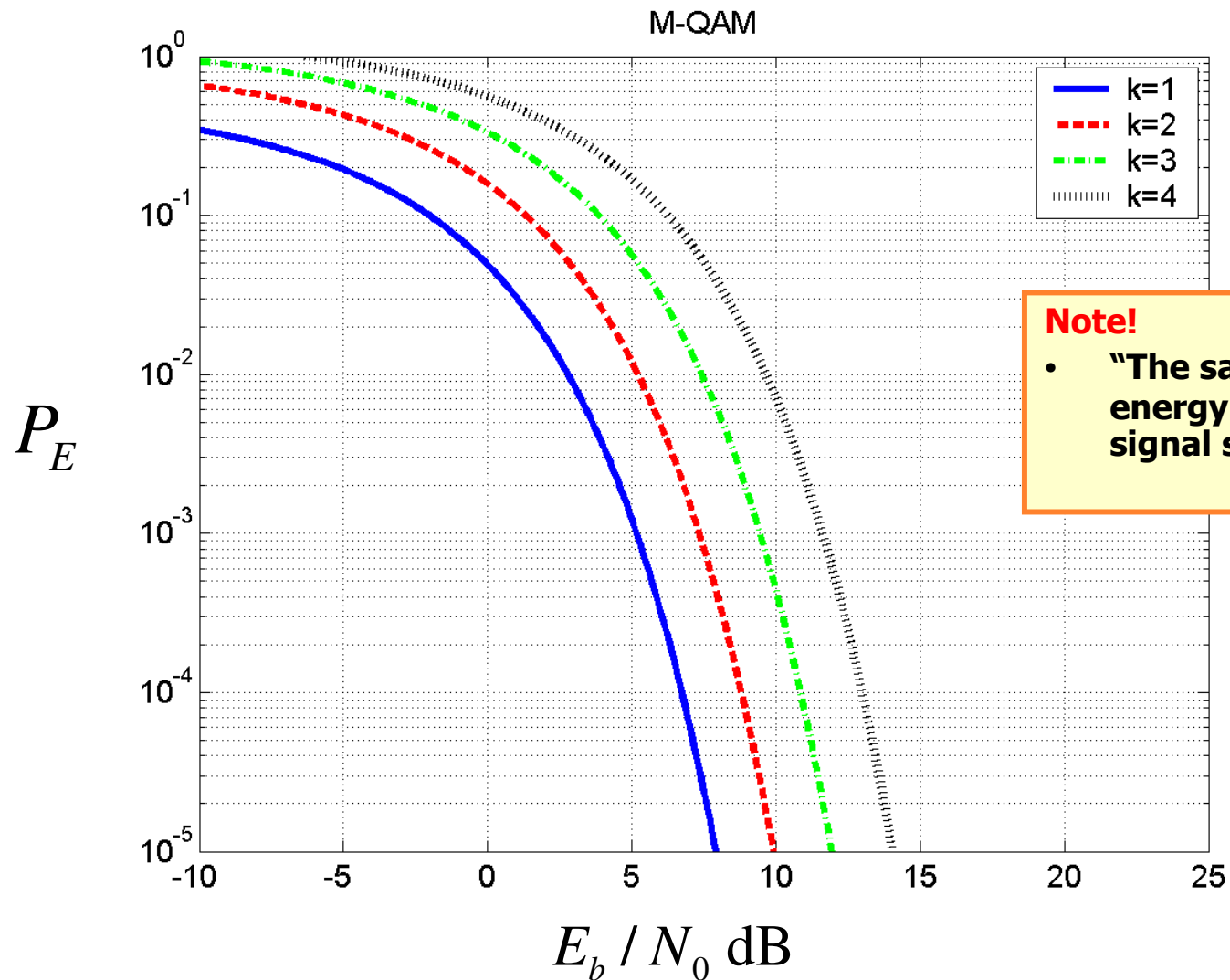


**Note!**

- “The same average symbol energy for different sizes of signal space”



# Probability of symbol error for M-QAM



**Note!**

- “The same average symbol energy for different sizes of signal space”

# Example of samples of matched filter output for some bandpass modulation schemes

